127.0.0.1 - - [24/Apr/2024 17:24:21] "POST /controllers/robot0Controller/ HTTP/1.1" 200 -

ERROR: 'C:/Users/nacho/Documents/Programacion/webots\_2023/erebus/game/protos/custom\_robot.proto':24:30: error: PROTO parameter 'camera\_width' has no matching IS field.

ERROR: 'C:/Users/nacho/Documents/Programacion/webots\_2023/erebus/game/protos/custom\_robot.proto':25:30: error: PROTO parameter 'camera\_height' has no matching IS field.

INFO: robot0Controller: Starting controller: python.exe -u robot0Controller.py

Device "camera1" was not found on robot "Erebus\_Bot"

Traceback (most recent call last):

File "C:\Users\nacho\Documents\Programacion\webots\_2023\erebus\game\controllers\robot0Controller\robot0Controller.py", line 107, in <module>

main()

File "C:\Users\nacho\Documents\Programacion\webots\_2023\erebus\game\controllers\robot0Controller\robot0Controller.py", line 100, in main

robot = Robot(time\_step=32)

File "C:\Users\nacho\AppData\Local\Temp\tmpl5g2vu17\robot\robot.py", line 56, in \_\_init\_\_

File "C:\Users\nacho\AppData\Local\Temp\tmpl5g2vu17\robot\devices\camera.py", line 44, in \_\_init\_\_

File "C:\Users\nacho\AppData\Local\Temp\tmpl5g2vu17\robot\devices\sensor.py", line 16, in \_\_init\_\_

File "C:\Users\nacho\AppData\Local\Temp\tmpl5g2vu17\robot\devices\sensor.py", line 8, in \_\_init\_\_

AttributeError: 'NoneType' object has no attribute 'enable' (ROBOT)

WARNING: 'robot0Controller' controller exited with status: 1.

**Error con la definición de los sensores**

AttributeError: 'Robot' object has no attribute 'center\_camera' (EXECUTOR)

**No posee la cámara central:**

* **def run(self): class ColorFilterTuner:**
* **def align\_with\_fixture(self): class CameraImage:**
* **def state\_report\_fixture(self, change\_state\_function): class CameraImage:**